

Learning, Detecting and Localizing 3D Object Classes from Arbitrary Viewpoints

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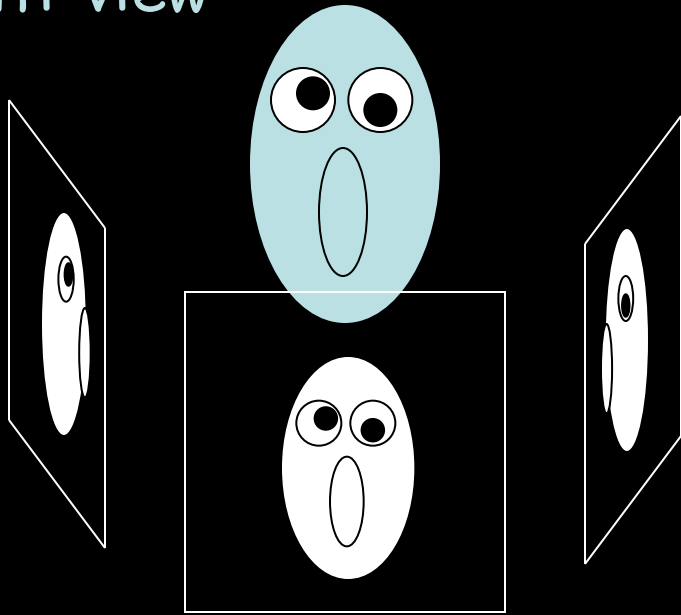
3dRR
2007



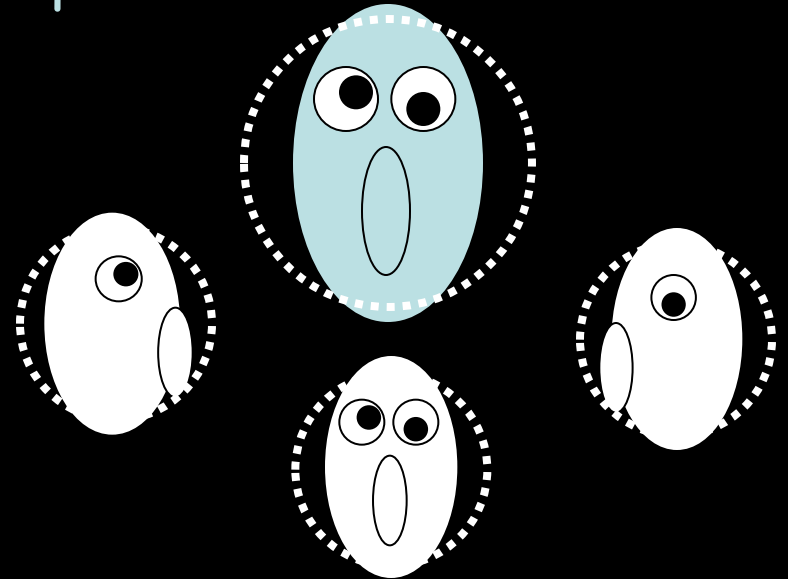
Multi-view vs. Viewpoint-Invariant

- Which to use?

Multi-view

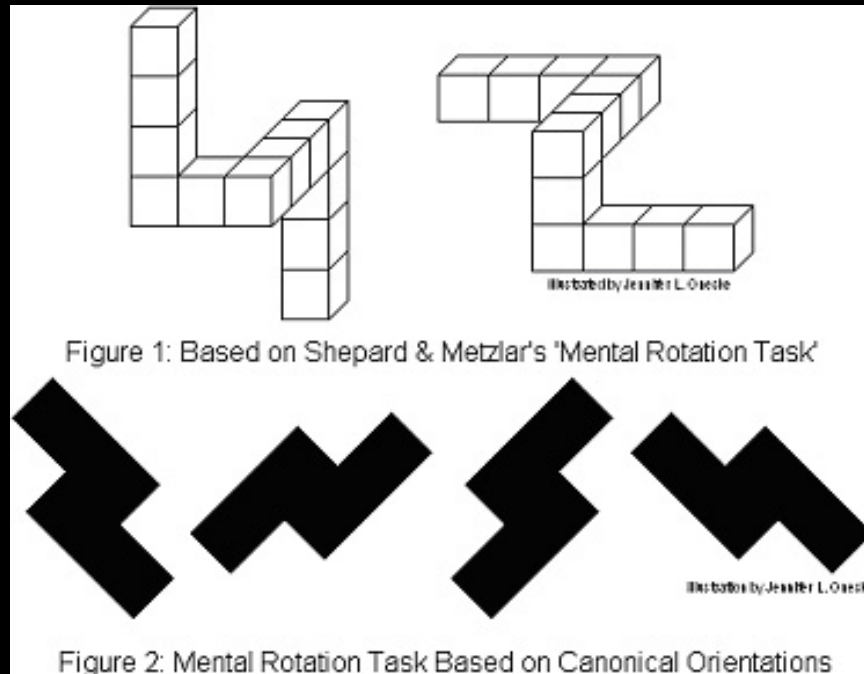


Viewpoint Invariant



Mental Rotation

- Time to decide if two 3D objects are similar is proportional to the angular difference between them



Roger Shepard &
Jacqueline Metzler, 1971

Recognition & Invariance

- Recognizing specific objects seems to be viewpoint-dependent
- Recognizing object classes seems to be viewpoint-invariant

Shimon Edelman
1995



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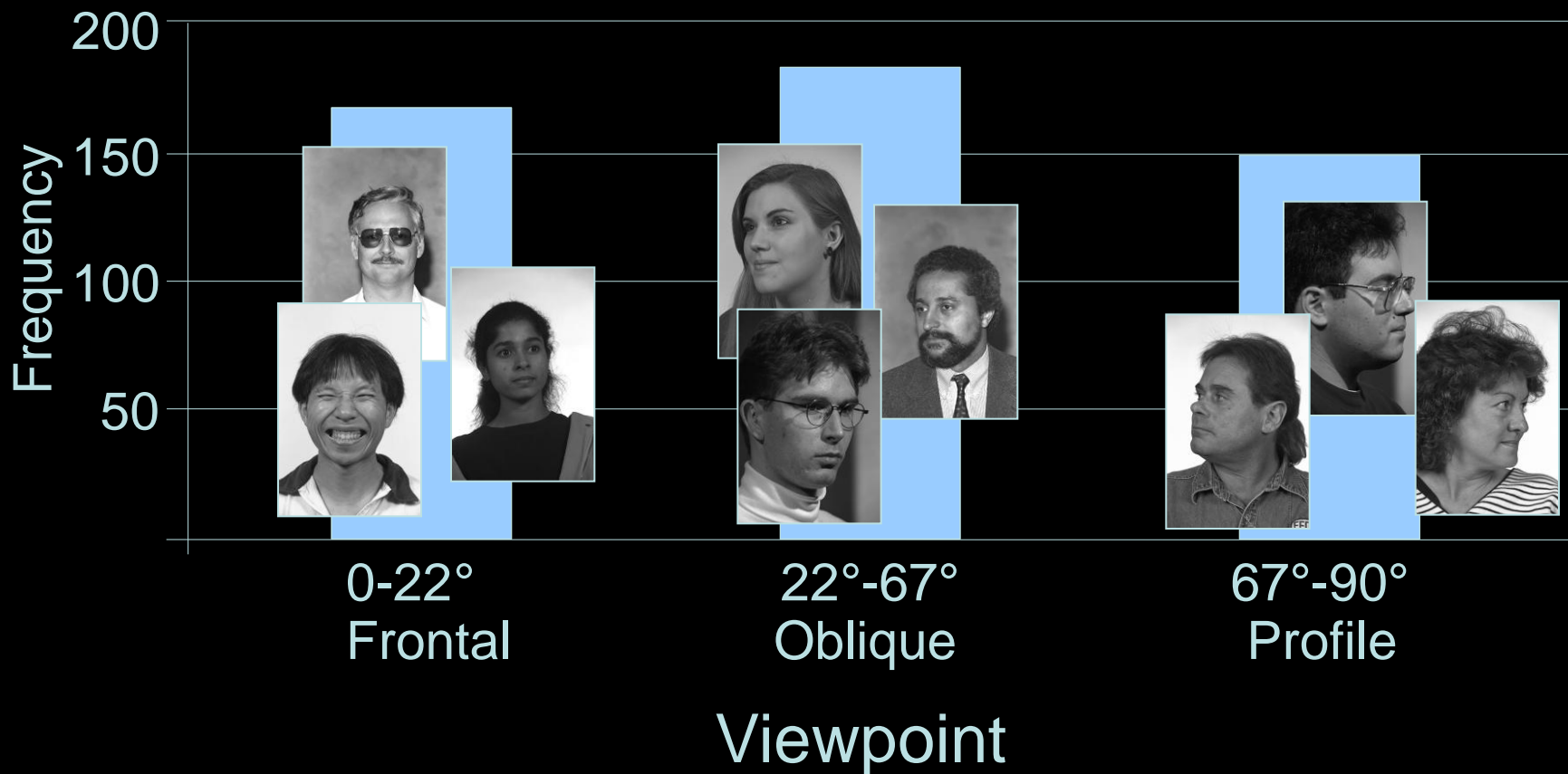


Methodology

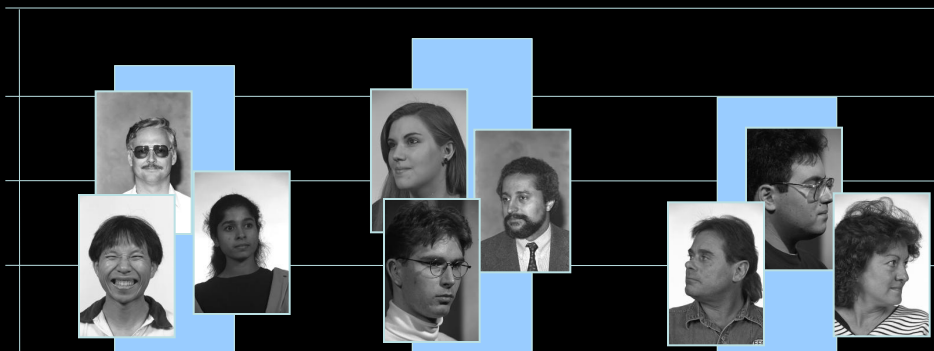
- Learn multi-view and viewpoint-invariant models from the same data.
- Compare detection performance.
- Data: faces, viewpoint variation.

Learning

- Color FERET database
 - 500 unique faces, viewpoint labels

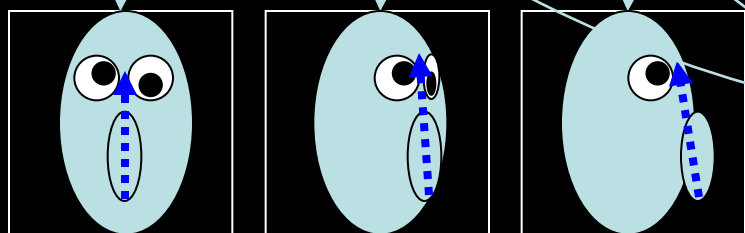


Learning



* Manually labelled OCIs

* Robust feature clustering

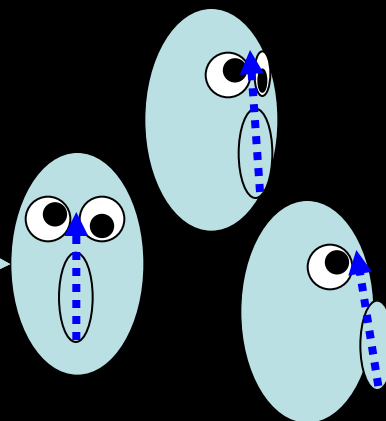


Frontal

Oblique

Profile

Multi-view Model

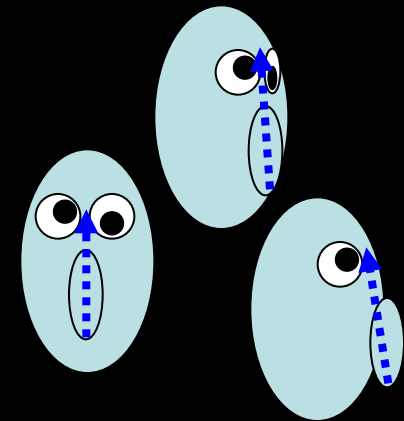


Viewpoint-invariant Model

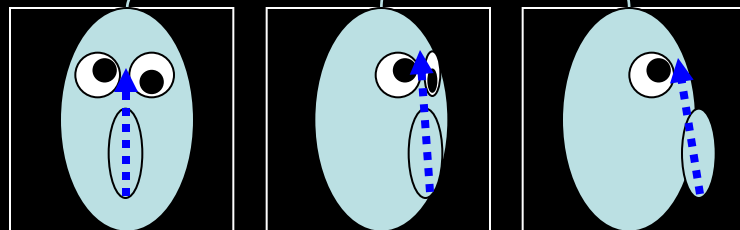
Detection and Localization



CMU Profile Database
(subset, 97 faces)



Viewpoint-invariant



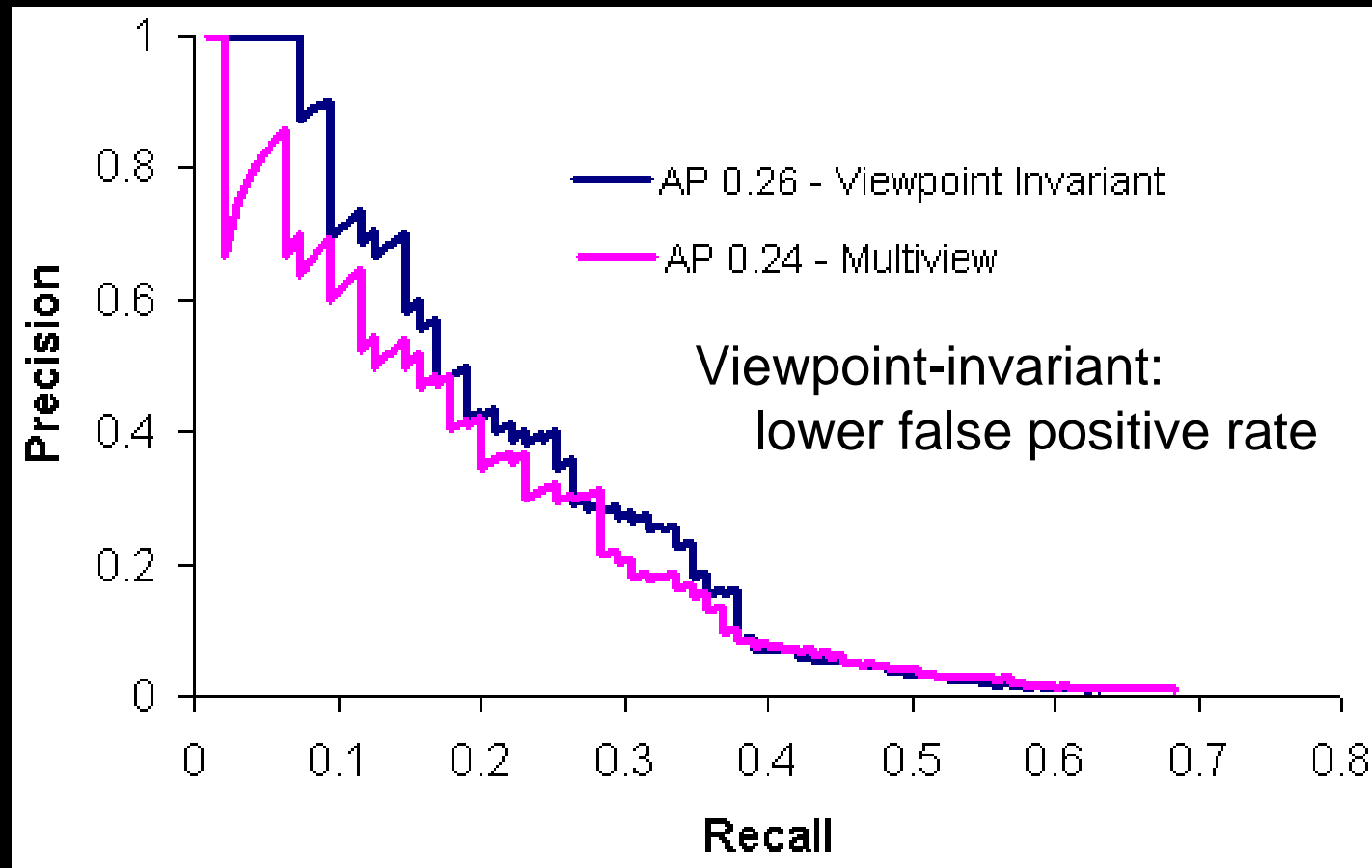
Frontal

Oblique

Profile

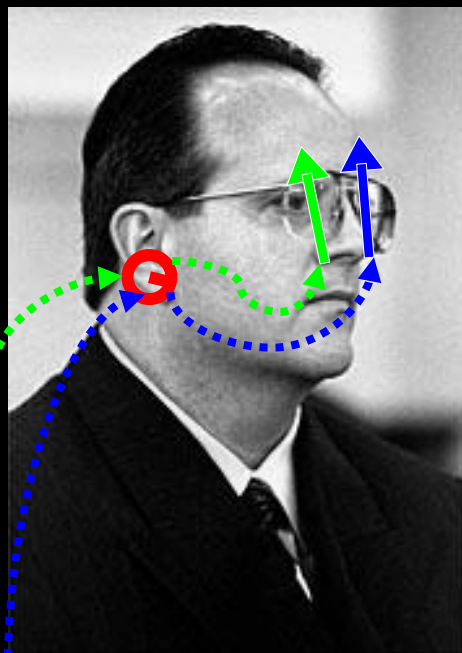
Multi-view

Detection Comparison

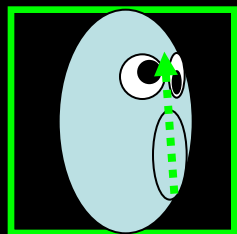
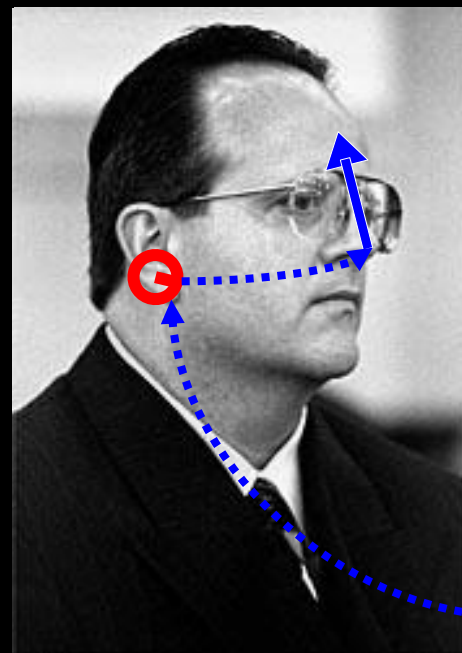


Example: Localization Ambiguity

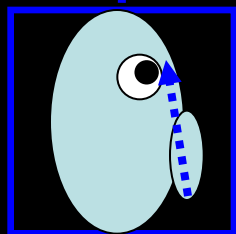
Multi-view
Detection



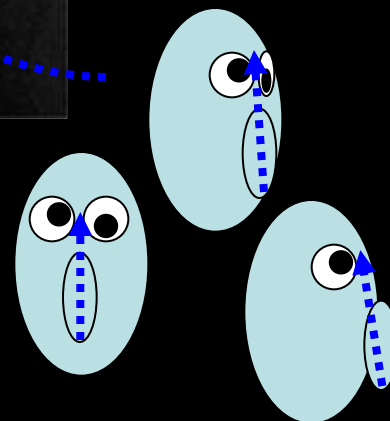
Viewpoint-Invariant
Detection



Oblique



Profile



Ambiguity Difficult to Resolve



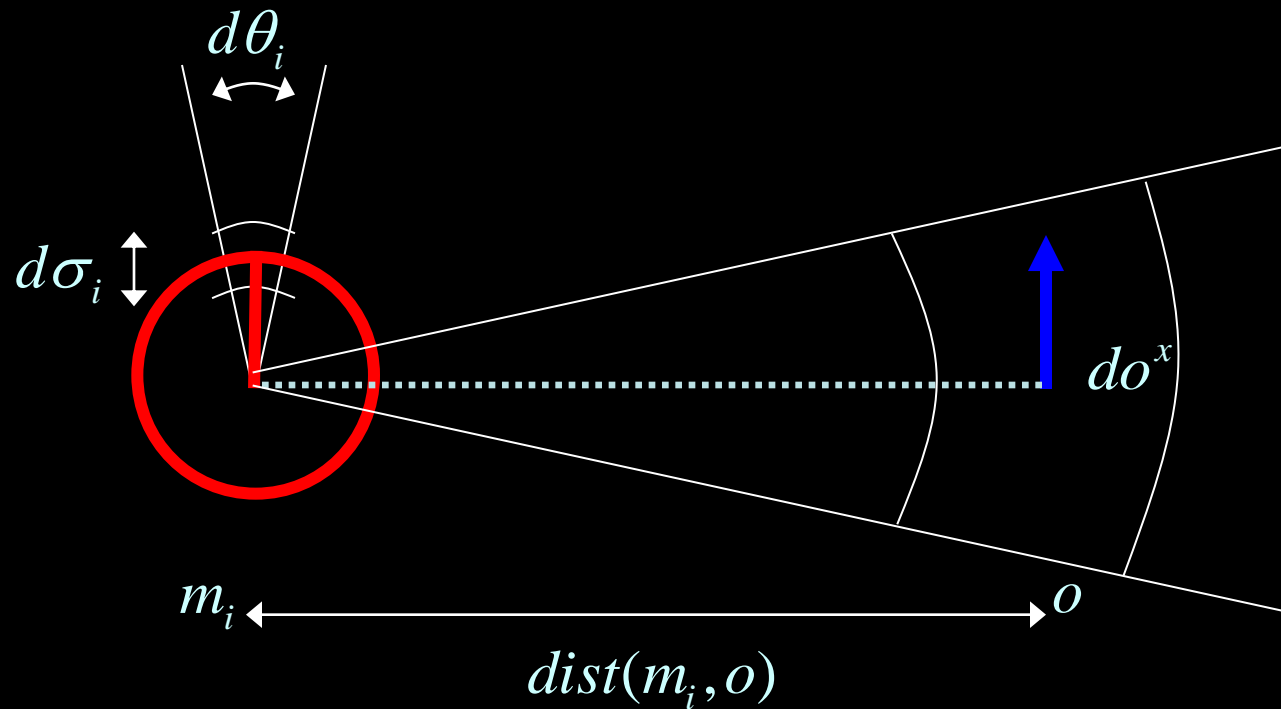
Choice of OCI

- Is nose-to-forehead OCI optimal?



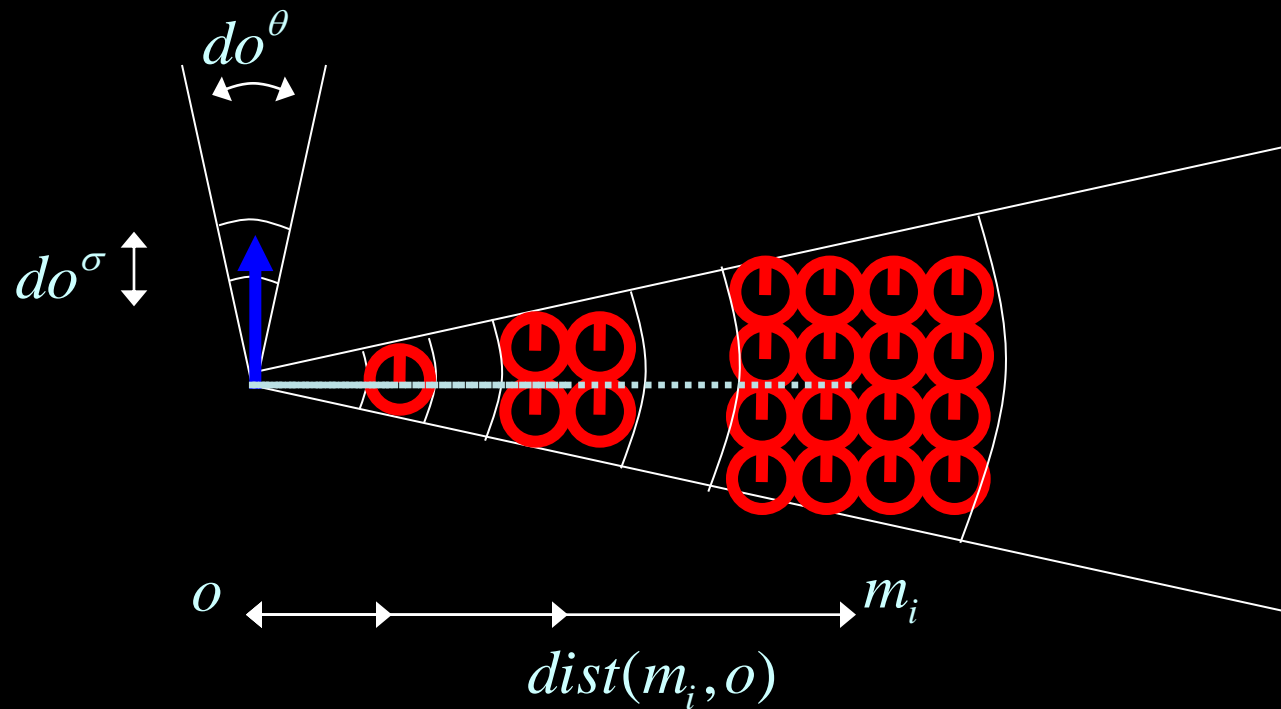
An Optimal OCI?

- Distance between feature and OCI
 - Related to OCI localization error do^x



An Optimal OCI?

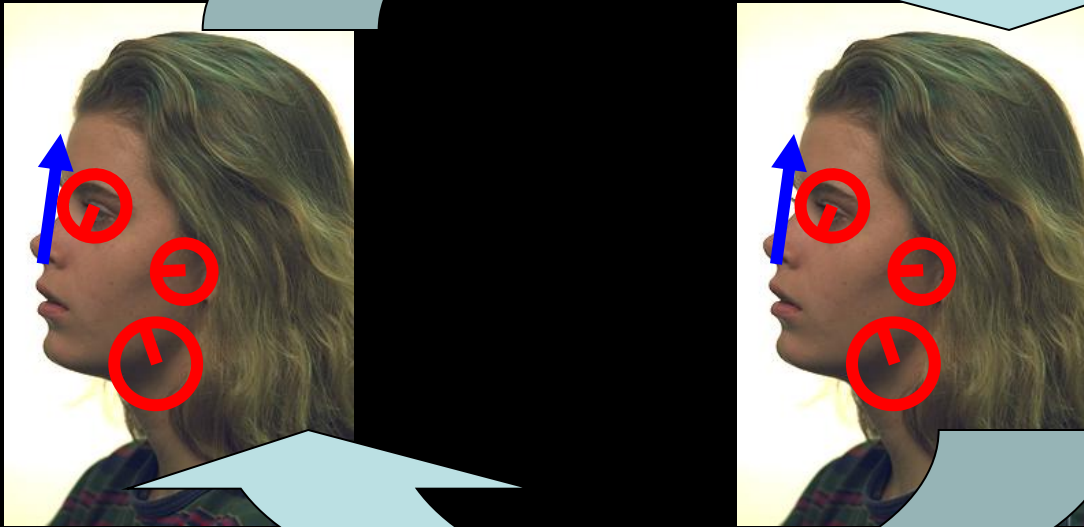
- Distance between feature and OCI
 - Related to probability of a false match



Data-driven OCI Estimation

Learn model features
from OCI

$$m_i \leftarrow p(m_i | o)$$

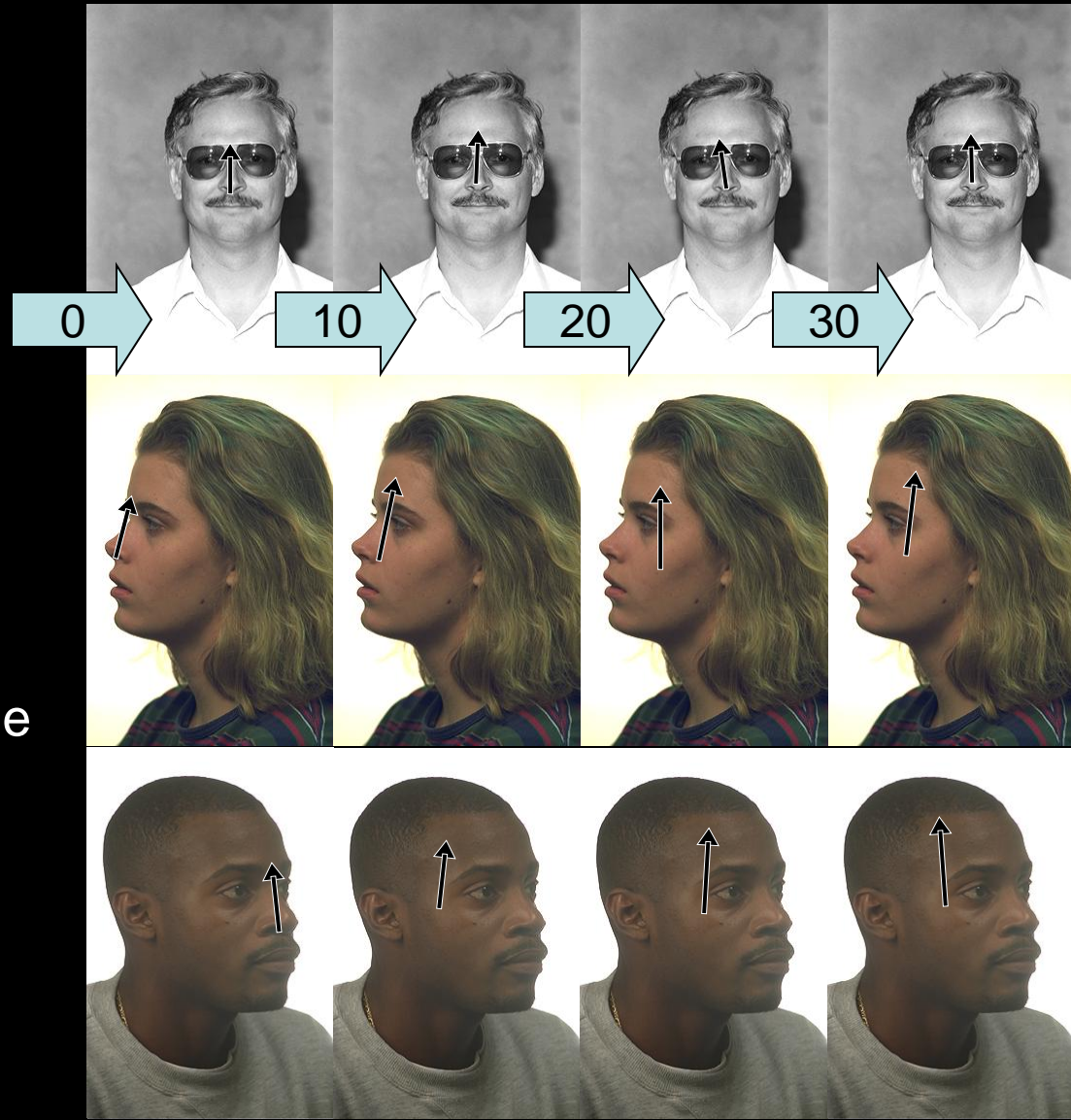


Estimate OCI
from model features

$$o \leftarrow \underbrace{\operatorname{argmax}}_o \left\{ \frac{p(o | \{m_i\})}{p(\bar{o} | \{m_i\})} \right\}$$

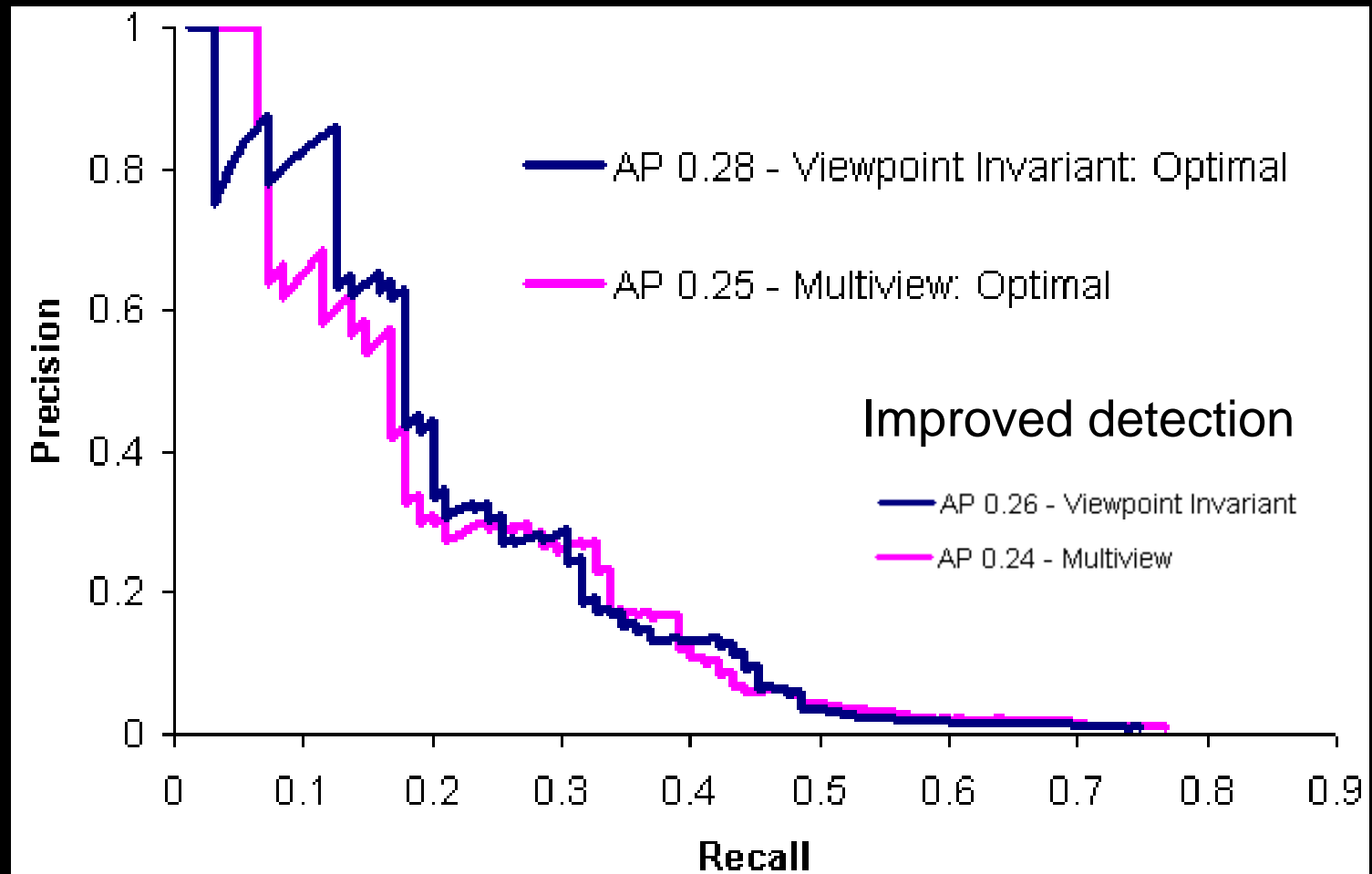
Data-driven OCI Estimation

30 Iterations



OCI remains consistent with 3D head in different views, different people

Comparison



Summary



- Viewpoint-invariant modeling
 - Features related directly to object class
 - Viewpoint information not required
 - Reduces localization ambiguity
- Data-driven OCI
 - Stable, minimizes OCI localization error
 - Consistent with 3D geometry of underlying object class